Solving polynomial equations in \mathbb{C} (section 1.1)

1) Every non-zero complex number z_0 has two square roots, i.e solutions z to

and they are opposites.
proof 1: Use the polar form, writing
$$z_0 = \rho e^{i\phi}$$
, $z = r e^{i\theta}$, with $r, \rho > 0$.
 $(r e^{i\theta})^2 = e^{i\phi}$, $z = r e^{i\theta}$, with $r, \rho > 0$.
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 $(r e^{i\theta})^2 = e^{i\phi}$, $z = r e^{i\theta}$, with $r, \rho > 0$.
 $r^2 e^{i(2\theta)} = e^{i\phi}$
 $1 = -\sqrt{e} e^{i\theta/2}$, $bcs e^{i\pi} = -1$.
 $r^2 e^{i(2\theta)} = e^{i\phi}$
 $i = e^{i\phi}$, $z = r e^{i\theta}$, $z = \sqrt{e} e^{i\theta/2}$, $bcs e^{i\pi} = -1$.
 $r^2 e^{i(2\theta)} = e^{i\phi}$
 $i = e^{i\phi}$, $z = r e^{i\phi}$, $z = r e^{i\theta}$, $e^{i\theta/2}$, $e^{i\theta/2}$, $e^{i\theta/2}$.
 $r^2 e^{i(2\theta)} = e^{i\phi}$
 $r^2 e^{i(2\theta)} = e^{i\phi}$
 $r^2 = e^{i\phi}$, $z = r e^{i\phi}$, $z = r e^{i\theta}$, $z =$

$$z_{0} = x_{0} + i y_{0}$$

$$z = x + i y$$

$$(x + i y)^{2} = x_{0} + i y_{0}$$

$$\begin{cases} x^{2} - y^{2} = x_{0} \\ 2 x y = y_{0} \end{cases}$$

$$z_{1} = x_{0} + i y_{0}$$

$$z_{2} = -z_{1}$$

Case 1: If $y_0 \neq 0$ then $x, y \neq 0$. Solve for y from the second equation and subsitute into the first:

$$x^{2} - \left(\frac{y_{0}}{2x}\right)^{2} = x_{0}$$

4 x⁴ - 4 x₀x² - y₀² = 0

Use the quadratic formula for real coefficients for x^2

$$x^{2} = \frac{4 x_{0} + \sqrt{16 x_{0}^{2} + 16 y_{0}^{2}}}{8} = \frac{x_{0} + \sqrt{x_{0}^{2} + y_{0}^{2}}}{2}$$

There are two opposite real values of x which solve this equation, with corresponding opposite values of $y = \frac{y_0}{2x}$.

Case 2: If $y_0 = 0$ it meant that $z_0 = x_0$ was real, and you already know how to find the two square roots. If $x_0 > 0$ they will be real square roots, and if $x_0 < 0$ they will be imaginary.

2) The general degree *n* polynomial equation

$$p(\mathbf{z}) := \mathbf{z}^n + a_{n-1}\mathbf{z}^{n-1} + \dots + a_1\mathbf{z} + a_0 = 0$$

$$a_{n-1}, \dots a_1, a_0 \in \mathbb{C}$$

You've been told forever that every degree n polynomial equation has *n* complex roots, counting multiplicty. This fact is known as "The Fundamental Theorem of Algebra." You'll learn a beautiful "elementary" proof of the fundamental theorem of algebra in this class. It's a proof by contradiction though, and except for very special polynomials there are no explicit formulas for exact solutions.....

- There is a very complicated cubic formula for cubic equations. There is also a formula
- for the roots of 4th order polynomials. The Abel-Ruffini Theorem asserts however, that there are no general formulas for the roots of degree 5 and higher polynomial equations, such that these formulas use only the algebraic operations of addition, multiplication, and taking radicals (square roots, cube roots, etc.). One of the founders of number theory, Évariste Galois, developed "Galois Theory", which explains exactly which special higher degree polynomial equations can be solved using these operations. These are topics in advanced algebra courses.

3) The special polynomial equation $z^n = 1$. h = 1, 3, 3, -Its solutions are called "the n^{th} roots of unity", and there are n of them.

Since complex multiplication in polar form reads

$$z w = r e^{i\theta} \rho e^{i\theta} = r \rho e^{i \cdot (\theta + \phi)},$$
(where $r = |z|, \theta = arg(z), \rho = |w|, \phi = arg(w)$), it's easy to check via induction, that
$$\begin{bmatrix} z^n = r^n e^{in\theta} \\ \vdots \\ z^n = r^n e^{in\theta} \end{bmatrix}$$
This formula for powers is known as "DeMoivre's formula".
induction $if = 2 = r e^{i\theta}$
 $h \equiv 1: 2 = r e^{i\theta}$

$$\begin{bmatrix} h \equiv 1: 2 = r e^{i\theta} \\ \vdots \\ z^{k+1} = 2^k ? = (r^k e^{ik\theta}) (r e^{i\theta})$$
mult $\pm r^{k+1} e^{i(k+1)\theta}$
So, to solve $z^n = 1$, express $z = |z| e^{i\theta}$ and solve
 $z^{n} = |z|^n e^{in\theta} = 1. = 1 e^{i\Theta}$

$$i = |z|^n e^{in\theta} = 1. = 1 e^{i\Theta}$$

$$i = 2\frac{\pi}{n} k$$

$$\frac{z^5 = \lambda}{i(\frac{2\pi}{n})} = 0 = 0, \frac{2\pi}{n}, \frac{2\pi}{n}, 2, \dots - \frac{2\pi}{n} (n-1), \frac{2\pi}{n} n \ge 0$$

$$i = \frac{2\pi}{n} k$$

Name <u>Solutions</u> Student I.D. 1 4200-001 Quiz week 1 August 26, 2020 Math 4200-001

1a) Express 8 *i* in polar form, using Euler's formula



1b) Find all sollutions z to the equation $z^3 = 8 i$.

$$Z = l \ge l e^{i0}$$

$$z^{3} = l \ge l^{3} e^{i30} = 8 e^{i\frac{\pi}{2}}$$

$$l | : | \ge l^{3} = 8 \implies | \ge l \ge 2$$

$$z = 2e^{i\frac{\pi}{6}}, 2e^{i\frac{\pi}{2}\pi}, 2e^{i\frac{\pi}{2}\pi}$$

$$(= -2i)$$

$$yon could also solve / express$$

$$sol'th in rectangular$$

$$conds$$

1c) Sketch 8 *i* and the three cube roots from part b, in the complex plane. Indicate how the absolute value and arguments of the roots relate to those of 8 *i*.

 $\frac{1}{8i = 8e^{i\pi/2}}$ See above, 8 (2 points) picture $\frac{5\pi}{2e^{i\pi/2}}$ 2e 28 $\sum_{b}^{5} \pi 2e^{i\pi/6}$ $\int -\pi/2 \sigma + \frac{3}{2}\pi$ -2i

Math 4200

Friday August 28

1.2-1.3 Algebra and geometry of complex arithmetic from Wednesday's notes; introduction to complex plane transformations section 1.3, in today's notes. We'll pick up in Wednesday's notes where we left off, and continue into today's.

Announcements: Office Hrs Tuesdays 2-3 (already MWF 1-2.)

Warm-up exercise:

Section 1.3, "basic" complex functions.

<u>Example 1</u> $f: \mathbb{C} \to \mathbb{C}, f(\mathbf{z}) = a \mathbf{z} + b \quad (a, b \in \mathbb{C}).$

Using polar form makes this transformation easy to understand geometrically. Write

$$\begin{cases} z = |z| e^{i \operatorname{arg} z}, \\ a = |a| e^{i \operatorname{arg} a}, \end{cases}$$

and compute f(z) in order to interpret it as the composition of a rotation, a scaling, and then a translation.

•

$$f(z) = az + b$$

$$f(z) = |a| e^{i a a a} (z| e^{i a a a^2} + b)$$

$$f_1(z) = e^{i a a a} 2$$

$$rotales 2 b$$

$$argle a$$

$$f_2(w) = |a| w scales$$

$$f = f_3 \cdot f_2 \cdot f_1$$

$$f_3(y) = y + b$$

$$g(z) = \sqrt{2} e^{i x + z a s f_1 + i x}$$

$$f_1(y) = y + b$$

$$g(z) = \sqrt{2} e^{i x + z a s f_1 + i x}$$

$$f(z) = \sqrt{2} e^{i x + z a s f_1 + i x}$$

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When we start discussing complex differentiability in section 1.5 we will want to go back and forth between discussions for complex-valued functions $f: \mathbb{C} \to \mathbb{C}$ and the mathematically equivalent discussions for related real functions $F: \mathbb{R}^2 \to \mathbb{R}^2$, so that we can take advantage of what you know about continuity and differentiability for real vector-valued functions, Math 3220.

The correspondence is that for each

$$f(\mathbf{z}) = f(x + i \frac{f: \mathbb{C} \to \mathbb{C}}{y) = u(x, y)} + i v(x, y)$$

with
$$u(x, y) = \operatorname{Re}(f(z)), v(x, y) = \operatorname{Im}(f(z)), \text{ there is}$$

 $F: \mathbb{R}^2 \to \mathbb{R}^2$
 $F(x, y) = (u(x, y), v(x, y)).$ we sometimes unit

And for each $F : \mathbb{R}^2 \to \mathbb{R}^2$ there is a corresponding $f : \mathbb{C} \to \mathbb{C}$.

If we apply this correspondence to the example on the previous page, with f(z) = a z + b and

$$z = x + i y$$
$$a = a_1 + i a_2$$
$$b = b_1 + i b_2,$$

then

$$f(x + iy) = (a_1 + ia_2)(x + iy) + (b_1 + ib_2)$$

= $(a_1x - a_2y + b_1) + i(a_2x + a_1y + b_2)$

If we write the corresponding real and imaginary components of F in column form we recognize certain affine transformations from linear algebra:

$$\vec{\mathsf{F}}(x,y) = \begin{bmatrix} u(x,y) \\ v(x,y) \end{bmatrix} = \begin{bmatrix} a_1 x - a_2 y + b_1 \\ a_2 x + a_1 y + b_2 \end{bmatrix} = \begin{bmatrix} a_1 & -a_2 \\ a_2 & a_1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$$

Recall your geometric matrix transformations of the plane from your linear algebra class to describe F geometrically on the next page, which will be equivalent to how we described f on the previous page.

$$\begin{bmatrix} a_{1} & -a_{2} \\ a_{2} & a_{1} \end{bmatrix} \xrightarrow{\text{Rot}} \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

$$= \sqrt{a_{1}^{2} + a_{2}^{2}} \begin{bmatrix} \frac{a_{1}}{\sqrt{2}} & -\frac{a_{2}}{\sqrt{2}} \\ \frac{a_{1}}{\sqrt{2}} & \frac{a_{1}}{\sqrt{2}} \end{bmatrix} \xrightarrow{\text{Rot}} \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

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$$f(x + iy) = (a_1 + ia_2)(x + iy) + (b_1 + ib_2)$$

= $(a_1x - a_2y + b_1) + i(a_2x + a_1y + b_2)$

$$F(x,y) = \begin{bmatrix} u(x,y) \\ v(x,y) \end{bmatrix} = \begin{bmatrix} a_1 x - a_2 y + b_1 \\ a_2 x + a_1 y + b_2 \end{bmatrix} = \begin{bmatrix} a_1 & -a_2 \\ a_2 & a_1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$$

$$+ ransleth b \int_{0}^{th} \int_{0}^{th} \sqrt{a_1^{2} + a_2^{2}} \int_{0}^{to} S\Theta - Six\Theta \int_{0}^{t} S \int_{0}^{t} \int_{0}^{t} \frac{b_1}{b_2} \int_{0}^{t} \frac{b_1}{b_2} \int_{0}^{t} F(x,y) = F_3 \circ F_2 \circ Rot_0 \int_{0}^{t} \int_{0}^{t} \int_{0}^{t} \frac{b_1}{b_2} \int_{0}^{t} \frac{f(x)}{b_2} \int_{0}^{$$